

The Siemens logo is displayed in a bold, teal, sans-serif font in the upper right corner of the slide. The background of the slide is a photograph of an offshore wind farm with several white wind turbines on a blue sea under a clear sky.

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## Part 2

# Distance Protection Special Cases

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Energy Sector

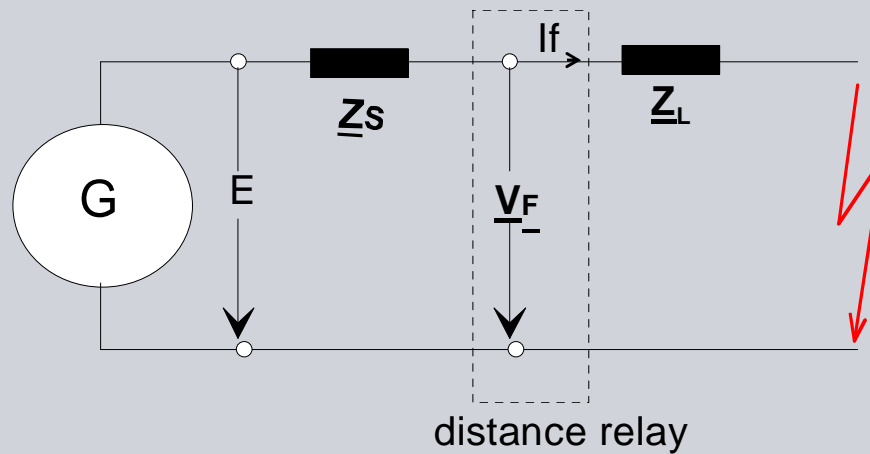
## For the application of distance protection

### Special Conditions:

1. Short lines/cables
2. Parallel lines
3. Fault resistance

## Short Lines: SIR - Definition

SIR (**S**ource **I**mpedance **R**atio) describes the ratio between the source impedance and the line impedance!



$$SIR = \frac{|Z_s|}{|Z_L|}$$

$$V_f = \frac{E}{1 + SIR}$$

High SIR = Small loop voltage  $V_f$  in case of a fault at the end of the line

Note: SIR trip time curves are mostly related to zone 1, i.e.  $Z_L = Z_1$

## SIR - Considerations about line length and infeed

The SIR gives some information about the power of infeed and the line length!

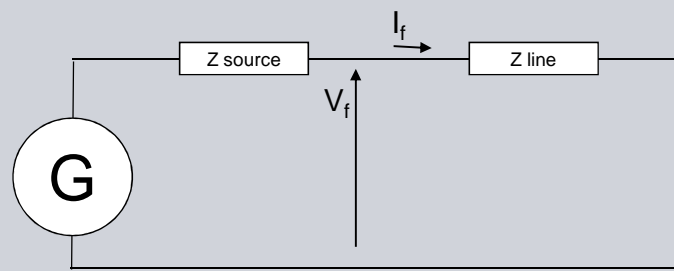
$SIR > 4$	short line*
$SIR < 4$ and $> 0.5$	medium line*
$SIR < 0.5$	long line*

For a distance relay the short line (large SIR) is more critical than on a long line (small SIR)!

\*Classification according IEEE-Guide

### Short Lines: Definition of the shortest zone 1 setting

The smallest reach setting of the underreaching Zone 1 will be determined with the minimum voltage measured for a fault at this zone boundary!



$$SIR = \frac{|Z_S|}{|Z_L|}$$

$$V_{-f} = \frac{E}{1 + SIR}$$

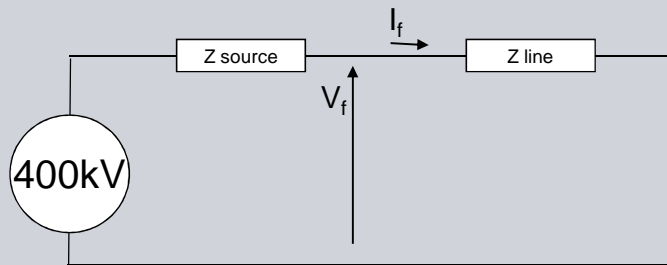
To ensure sufficient measuring accuracy a minimum voltage must be available for a fault at the boundary of the zone 1 setting. By definition of the loop impedances a 3ph fault will result in the smallest voltage:

V<sub>min</sub>=minimum voltage for measured accuracy in stated tolerance (e.g. 5%)

The shortest line length (zone 1 setting) is therefore defined by V<sub>min</sub> and the SIR.

### Short Lines: Example - shortest zone 1 setting

With minimum short circuit level on the busbar = 4 GVA, what is the smallest possible zone 1 setting is  $V_{min} = 0.5V$  secondary?



$$SIR = \frac{|Z_S|}{|Z_L|}$$

$$V_f = \frac{E}{1 + SIR}$$

$$Z_{source} = \frac{U_N^2}{S_{3ph}} = \frac{400^2}{4000} = 40\Omega$$

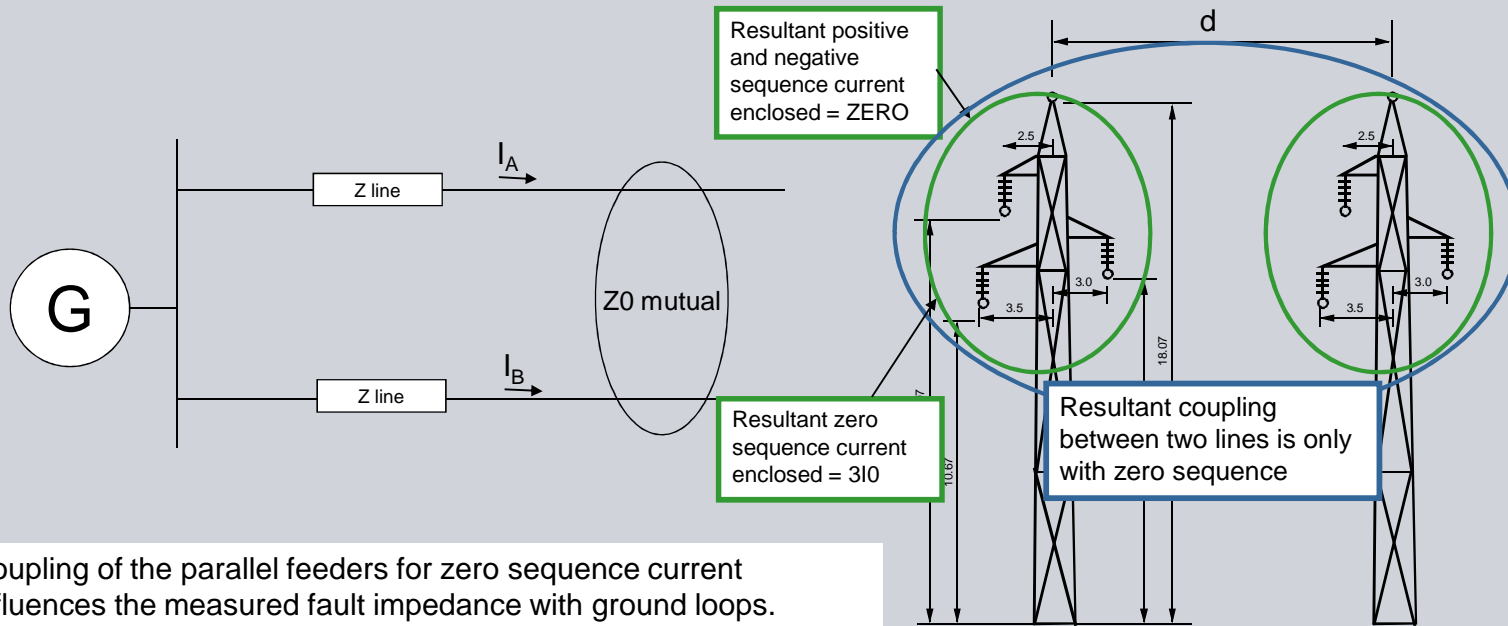
$$V_{min\_prim} = \frac{0.5}{100} \cdot 400kV = 2kV$$

$$SIR_{max} = \frac{E}{V_{min}} - 1 = \frac{400}{\sqrt{3} \cdot 2} - 1 = 114$$

$$Z1_{min} = \frac{Z_{source}}{SIR_{max}} = \frac{40}{114} = 0.35\Omega$$

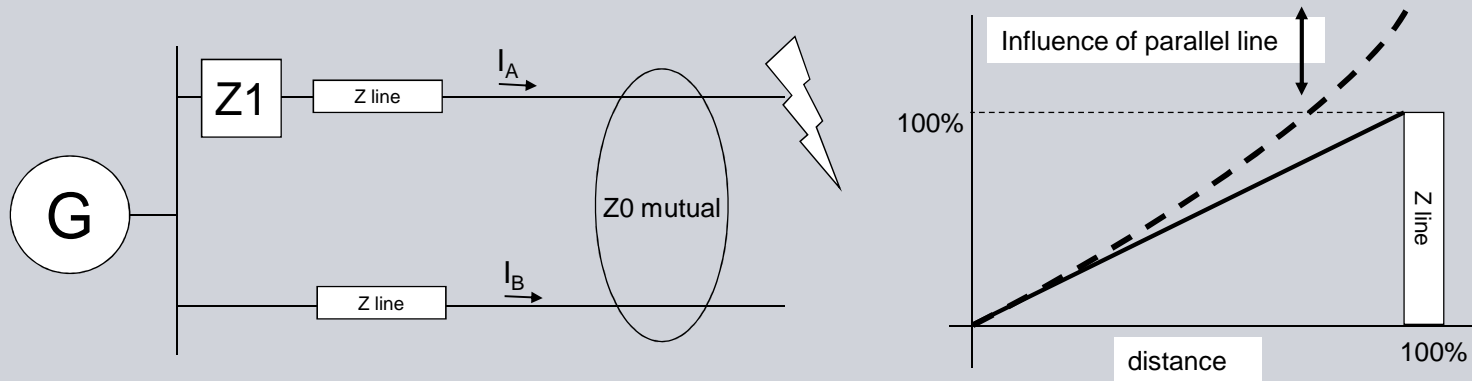
The shortest line length (zone 1 setting) is 0.35 Ohm primary. For a typical line reactance of 0.3 Ohm/km this corresponds to a line length of just over 1km.

# Parallel lines: Influence on distance measurement



Coupling of the parallel feeders for zero sequence current influences the measured fault impedance with ground loops.

## Parallel lines: Influence on distance measurement



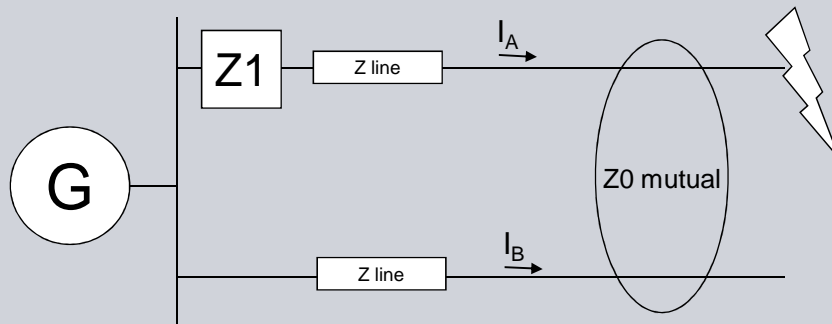
The loop voltage measured by Z1 for a single phase to ground fault as shown:

$$U_{L-G} = I_L \cdot Z_{Line} - I_{E\_A} \cdot Z_E - I_{E\_B} \cdot \frac{Z0_M}{3}$$

The measured loop impedance:

$$Z_{L-G} = Z_{Line} - \frac{I_{E\_B} \cdot \frac{Z0_M}{3}}{I_L - K0 \cdot I_{E\_A}}$$

## Parallel lines: Compensation with modified XE/XL



For compensation, influence of the parallel by  $X_{0M}$  is considered:

$$U_{L-G} = I_L \cdot X_L - I_{E-A} \cdot X_E - I_{E-B} \cdot \frac{X_{0M}}{3}$$

$$K_{X0} = \frac{XE}{XL}$$

$$K_{X0M} = \frac{X0M}{3XL}$$

$$r_{I0} = \frac{I_{E-B}}{I_{E-A}}$$

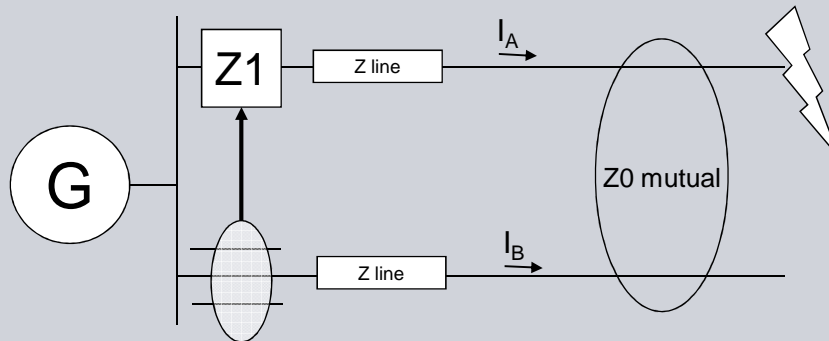
$$K_{X0}' = K_{X0} + K_{X0M} \cdot r_{I0}$$

The measured loop reactance with modified  $XE/XL = K_{X0}'$ :

$$X_{L-G} = \frac{I_L \cdot X_L - I_{E-A} \cdot X_E - I_{E-B} \cdot \frac{X_{0M}}{3}}{I_L - K_{X0}' \cdot I_{E-A}} = X_{Line}$$

## Parallel lines: Compensation with measured IE of parallel line

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The loop voltage measured by Z1 for a single phase to ground fault as shown:

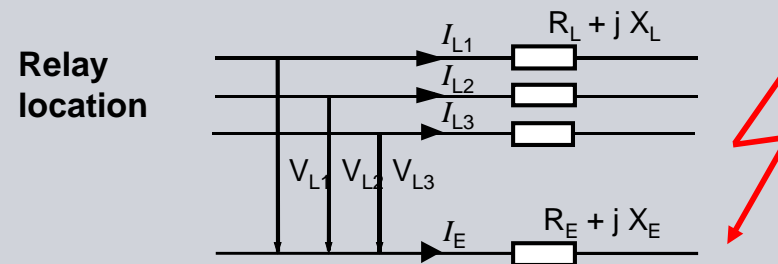
$$U_{L-G} = I_L \cdot Z_{Line} - I_{E\_A} \cdot Z_E - I_{E\_B} \cdot \frac{Z0_M}{3}$$

The measure loop impedance with modified parallel line compensation:

$$Z_{L-G} = \frac{I_L \cdot Z_{Line} - I_{E\_A} \cdot Z_E - I_{E\_B} \cdot \frac{Z0_M}{3}}{I_L - K0 \cdot I_{E\_A} - KOM \cdot I_{E\_B}} = Z_{Line}$$

## Distance measurement Fault loop formulas

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Phase-to-Earth loop:

$$\underline{V}_{L1} = \underline{I}_{L1} \cdot (R_L + jX_L) - \underline{I}_E \cdot (R_E + jX_E)$$

$$\underline{V}_{L1} = (\underline{I}_{L1} \cdot R_L - \underline{I}_E \cdot R_E) + j(\underline{I}_{L1} \cdot X_L - \underline{I}_E \cdot X_E)$$

$$\underline{V}_{L1} = R_L \cdot \left( \underline{I}_{L1} - \frac{R_E}{R_L} \cdot \underline{I}_E \right) + jX_L \left( \underline{I}_{L1} - \frac{X_E}{X_L} \cdot \underline{I}_E \right)$$



**Line and earth impedance are measured**

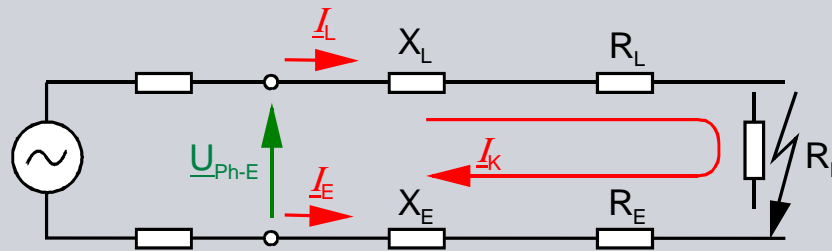
Phase-to-Phase loop:

$$\underline{V}_{L1-L2} = (R_L + jX_L) \cdot (\underline{I}_{L1} - \underline{I}_{L2})$$



**Only the Line impedance is measured**

# (Ph-E-loop) - influence of fault resistance with setting RE/RL and XE/XL - Siemens method

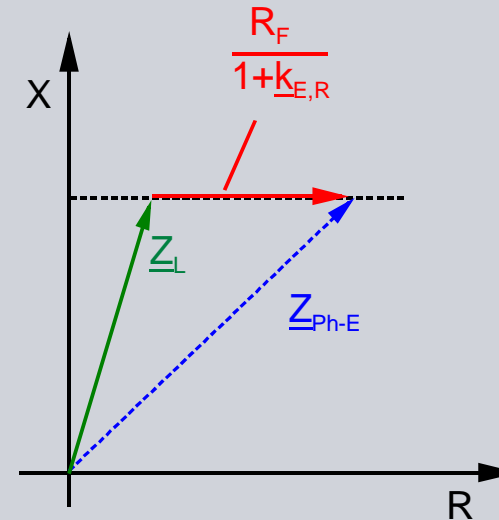


$$\underline{U}_{Ph-E} = \underline{I}_L (\underline{R}_L + j \underline{X}_L) - \underline{I}_E (\underline{R}_E + j \underline{X}_E) + R_F \cdot \underline{I}_L$$

$$X_{Ph-E} = \frac{\text{Im} \left[ \frac{\underline{U}_{Ph-E}}{\underline{I}_L} \right]}{1 + \frac{X_E}{X_L}} = X_L$$

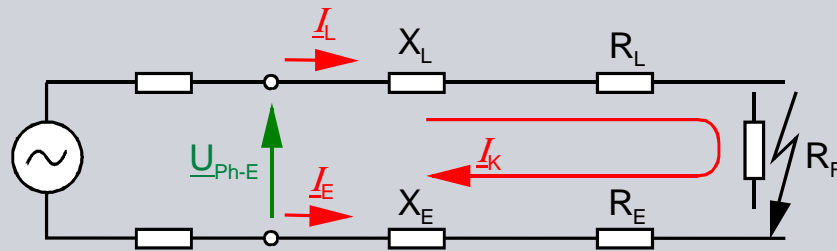
$$R_{Ph-E} = \frac{\text{Re} \left[ \frac{\underline{U}_{Ph-E}}{\underline{I}_L} \right]}{1 + \frac{R_E}{R_L}} = R_L + \frac{R_F}{1 + k_{E,R}}$$

with  $I_E = -I_L$



No measuring error in the X-direction

**(Ph-E-loop) - influence of fault resistance with separation **SIEMENS** of fault and line resistance - Not Siemens method**



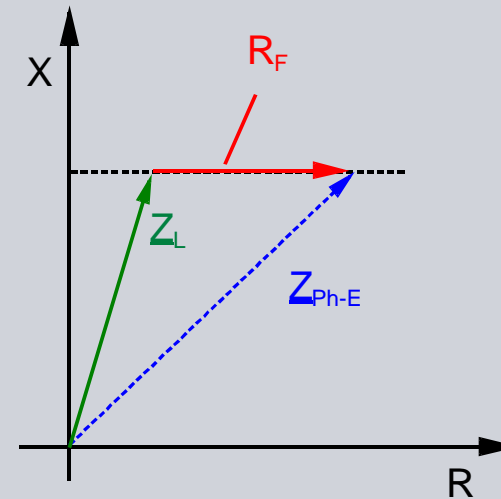
$$\underline{U}_{Ph-E} = \underline{I}_L (\underline{R}_L + j \underline{X}_L) - \underline{I}_E (\underline{R}_E + j \underline{X}_E) + R_F \cdot \underline{I}_L$$

$$X_{TypeC} = \frac{\text{Im}\{\underline{U}/\underline{I}\}}{1 + K_x} = X_L$$

with  $I_E = -I_L$

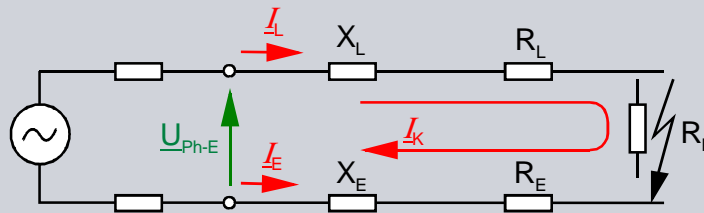
$$R_{TypeC} = \text{Re}\{\underline{U}/\underline{I}\} - X_{TypeC} / \tan(\varphi_L) \cdot K_r$$

$$R_{TypeC} = R_L + R_F$$



Note difference in fault resistance coverage with same zone setting!

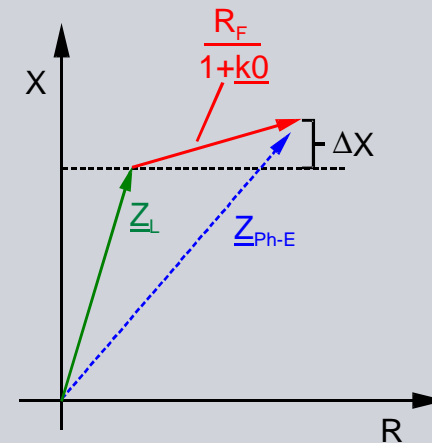
# (Ph-E-loop) - influence of fault resistance with complex KO setting - Not Siemens method



This method is not used by SIEMENS

$$\underline{U}_{Ph-E} = \underline{I}_L (\underline{Z}_L + \underline{Z}_E) + R_F \cdot \underline{I}_L \quad \text{assume } \underline{I}_L = -\underline{I}_E$$

$$\underline{Z}_{Ph-E} = \frac{\underline{U}_{Ph-E}}{\underline{I}_L - \underline{k}0 \cdot \underline{I}_E} = \underline{Z}_L \cdot \frac{1 + \frac{\underline{Z}_E}{\underline{Z}_L}}{1 + \underline{k}0} + \frac{R_F}{1 + \underline{k}0}$$



If  $\underline{k}0$  setting adapted to  $\frac{\underline{Z}_E}{\underline{Z}_L}$ , then  $\underline{Z}_{Ph-E} = \underline{Z}_L + \frac{R_F}{1 + \frac{\underline{Z}_E}{\underline{Z}_L}} = \underline{Z}_L + \frac{R_F}{1 + \left| \frac{\underline{Z}_E}{\underline{Z}_L} \right| \cdot e^{j(\varphi_E - \varphi_L)}}$



Also an additional measuring error in the X-direction